

CR7 CR12 CR18 CR20

Specifications

Payload	7 kg	12 kg	18 kg	20 kg
Reach	988 mm	1,434 mm	1,062 mm	1,798 mm
Weight (including built-in controller)	About 27 kg	About 43 kg	About 40 kg	About 75 kg
Degrees of freedom	6	6	6	6
MTBF	> 80,000 h	> 80,000 h	> 80,000 h	> 80,000 h
Power supply	Single-phase 90-264VAC, frequency 47-63Hz / 48VDC			Single-phase 180V ~ 264VAC, frequency 47-63Hz / 48VDC
Programming	Direct teaching control and graphical interface			

Performance

Typical Power	300 w	500 w	600 w	1000 w
Safety	Over 21 adjustable safety features including collision detection, virtual walls, and collaboration mode.			
Certification	EN ISO 13849-1, EN ISO 10218-1/ PL d, Cat. 3; ISO 15066, and EU CE marking requirements, KCs marking requirements, EAC marking requirements			
Force sensing (tool flange)	Force, x-y-z	Torque, x-y-z	Force, x-y-z	Torque, x-y-z
Force measurement resolution	0.1 N	0.02 Nm	0.1N	0.02Nm
Relative accuracy of force control	0.5 N	0.1 Nm	0.5N	0.1Nm
Adjustable range of Cartesian stiffness	0~3,000 N/m, 0~300 Nm/rad	0~3,000 N/m, 0~300 Nm/rad	0~3,000 N/m, 0~300 Nm/rad	0~3,000 N/m, 0~300 Nm/rad

Motion

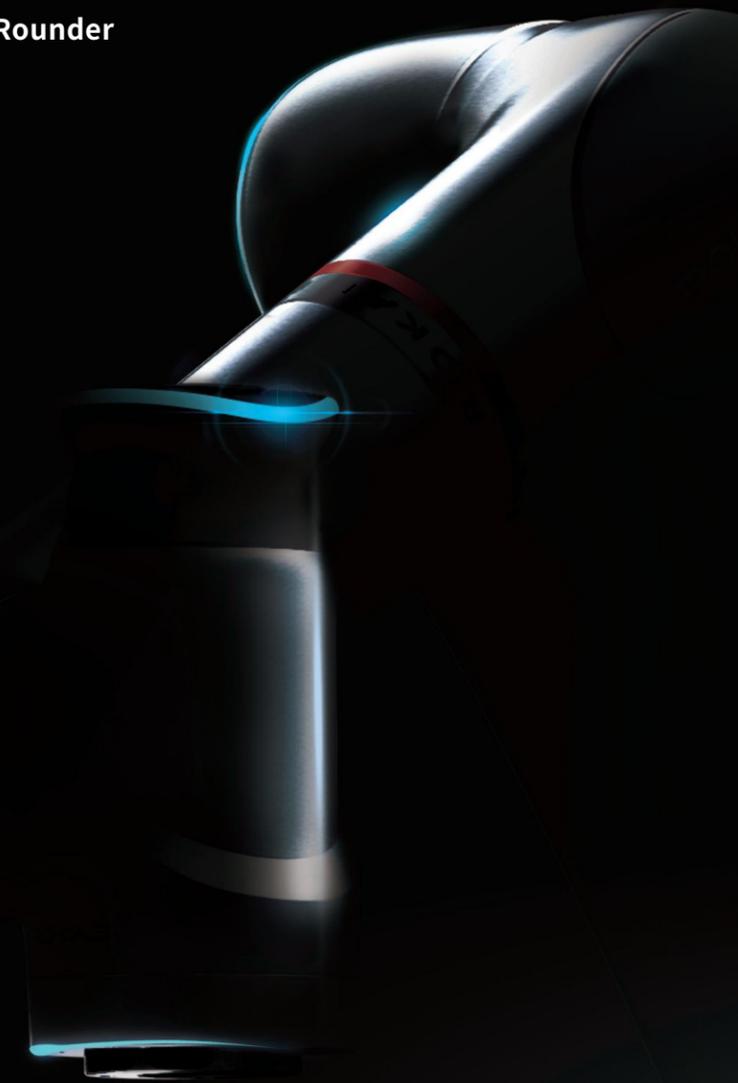
Repeatability	±0.02 mm		±0.03 mm		±0.03 mm		±0.05 mm	
Motion joint	Working range	Maximum speed						
Axis 1	±360°	180°/s	±360°	120°/s	±360°	120°/s	±360°	120°/s
Axis 2	±360°	180°/s	±170°	120°/s	±170°	120°/s	±360°	120°/s
Axis 3	±360°	234°/s	±360°	180°/s	±165°	180°/s	±170°	120°/s
Axis 4	±360°	240°/s	±360°	234°/s	±360°	180°/s	±360°	180°/s
Axis 5	±360°	240°/s	±360°	240°/s	±360°	180°/s	±360°	234°/s
Axis 6	±360°	300°/s	±360°	240°/s	±360°	180°/s	±360°	234°/s
Axis 7	—		—		—		—	
Maximum speed at tool end	≤ 3.2 m/s		≤ 3.0 m/s		≤ 3.0 m/s		≤ 3.5 m/s	

Considering the upgrade of the product, the actual parameters of the product shall be subject to the corresponding hardware installation manual

Physical properties

IP rating	IP54
ISO cleanroom class	5
Noise	≤ 70 dB(A)
Robot installation	At any angle
Tool I/O ports	2 Digital outputs, 2 Digital inputs, 2 Analog inputs
Tool communication interface	RS485(Alternative with two analog input pins, can not be used simultaneously)
Tool I/O power supply	12V/24V 1A
Pedestal common I/O ports	4 Digital outputs, 4 Digital inputs, 2 safety input, 1 safety output
Pedestal communication interface	1 channels Ethernet
Pedestal output power supply	24V, 1.5A
Operating ambient temperature	0°C~50°C
Humidity	≤ 93% RH (non-condensing)

CR Series Flexible Collaborative Robots
A Powerful Yet Flexible All-Rounder



ROKAE Robotics

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CR Series

Flexible Collaborative Robots

The new **xMate CR** series flexible collaborative robots are built on the force-position hybrid control framework and xCore, a new self-developed high-performance control system for industrial robots. Designed for industrial applications, the robots deliver improved motion performance, force control, safety, ease of use, and reliability. This makes it an ideal choice for different applications in various industries, helping enterprises implement flexible production quickly.



Model CR7
Payload 7 kg
Reach 988 mm

Model CR12
Payload 12 kg
Reach 1,434 mm

Model CR18
Payload 18 kg
Reach 1,062 mm

Model CR20
Payload 20 kg
Reach 1,798 mm

Applications

xMate CR series flexible collaborative robots can undertake a variety of tasks, including

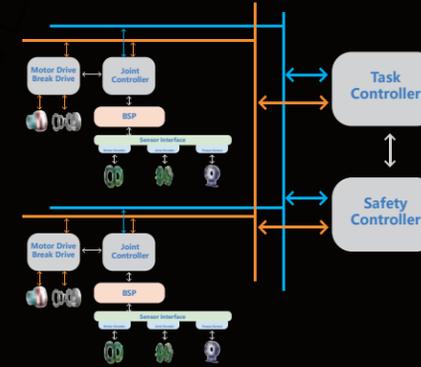
- Compliant assembly
- Screw locking
- Deburring and grinding
- Handling
- Loading and unloading
- Material removal
- Packaging and palletizing
- Welding

Driving improved productivity and flexible automation for companies of all sizes.



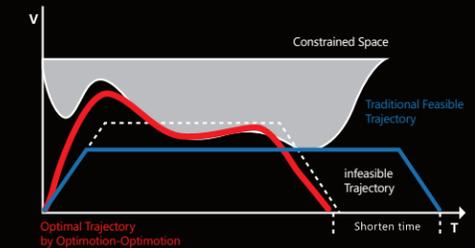
Extreme Safety

Suction band-type brakes, independently certified safety controllers, more than 21 TÜV functional safety features, and ultrasensitive collision detection by torque sensors, comprehensively ensure a safer human-machine collaboration.



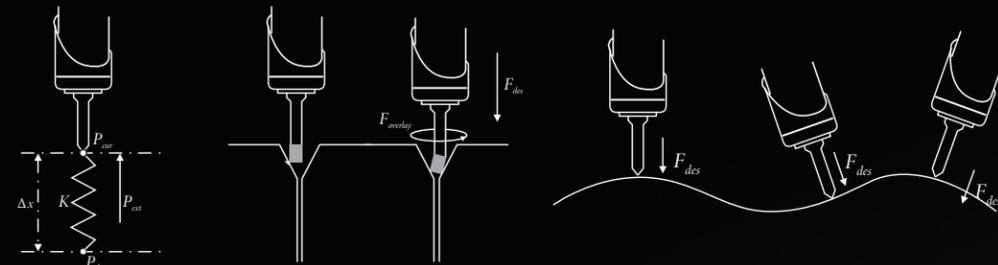
Superior Performance

Cutting-edge motion control technologies for industrial robots to deliver first-class path accuracy, combined with customized motor drive control systems, create a powerful performance.



Compliant Flexibility

By adopting force-position hybrid control technology, highly dynamic force control is integrated into robot joints, which provides compliance control close to human hands, while the force control process kit helps greatly enhance force control task efficiency with no additional extensions required.



Ease of Use

Fast installation and flexible deployment thanks to the cabinet-free design, direct teaching control, and graphical programming enable greater ease of use. Applicable to a variety of application scenarios by supporting most extensions in the industrial ecosystem.



Excellent Reliability

100+ design verification experiments, and 20+ factory tests, build them into an ideal choice for industrial applications.



A Powerful Yet Flexible All-Rounder |