

MZ12H COMPACT MULTIPURPOSE ROBOT

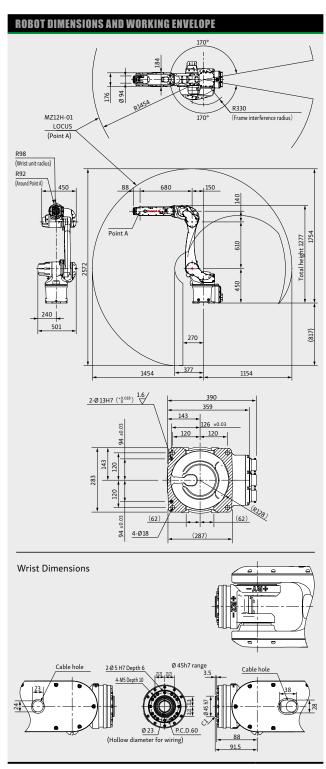


- ► Fully enclosed robot body and wrist: Supports various applications with IP67 equivalent, rust proof
- ► Achieves high speed & precise motion control through weight reduction and Improved rigidity Increases productivity
- ► Integrated valves in the arm and smart cable and hose routing through the hollow wrist Minimizes interference and wear

| BASIC SPECIFICATION OF ROBOT | | |
|--|-------|---|
| ltem | | Specifications |
| Robot model | | MZ12H-01 |
| Structure | | Articulated |
| Number of axes | | 6 |
| Max. reach | | 1454mm |
| Installation | | Floor / Inverted mount / Tilted |
| Drive system | | AC Servodrive |
| Max. working envelope | J1 | ±2.97rad (±170°) |
| | J2 | +1.57~-2.79rad (+90~-160°) |
| | J3 | +3.67~-2.57rad (+210~-147°) |
| | J4 | ±3.32rad (±190°) |
| | J5 | ±2.44rad (±140°) |
| | J6 | ±6.28rad (±360°) |
| Max. speed*1 | J1 | 4.54rad/s (260°/s) |
| | J2 | 4.01rad/s (230°/s) |
| | J3 | 4.54rad/s (260°/s) |
| | J4 | 8.20rad/s (470°/s) |
| | J5 | 8.20rad/s (470°/s) |
| | J6 | 12.92rad/s (740°/s) |
| Payload (max.) | Wrist | 12kg |
| Allowable static load torque | J4 | 26.5N•m |
| | J5 | 26.5N•m |
| | J6 | 12.0N•m |
| Allowable moment of inertia*2 | J4 | 0.9kg•m² |
| | J5 | 0.9kg•m² |
| | J6 | 0.3kg•m² |
| Position repeatability*3 | | ±0.04mm |
| Air piping | | Ø6×2, Ø8×1 |
| Application signal wires | | 24 wires (including wires for the optional solenoid valves) |
| Ambient conditions | | Ambient temperature: 0~45°C*4 Ambient humidity: 20~85% RH (without condensation) Vibration: Not more than 0.5G (4.9m/s²) |
| Dust-proof/ Drip-proofperformance*5 | | IP67 equivalent (Protection Rating) |
| Robot mass | | 155kg |

1(rad) = 180/π (°), 1 (N•m) = 1/9.8 (kgf•m)

- ► Flexible system designs possible utilising the wide working envelope
- Large wrist torque supports large and heavy tooling and work pieces
- ▶ Integrated wiring at the wrist for 7th axis & Ethernet
- ► Neat cable and hose routing



Note: Explosion-proof version is not available.
Specifications are subject to change without prior notice for technical changes.

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^{*1} The maximum velocity in the chart is the maximum value.

It will change depending on the operation program and the wrist load condition.

^{*2} Depends on wrist load condition.

^{*3} JIS B 8432 conformance.

^{*4} Up to a maximum of 1000m from sea level. Ambient temperature is reduced when allowable altitude is exceeded.

^{*}s Fluids that cause the deterioration of sealants, such as gasoline-based cutting fluids, chlorine, alkalines, acids and organic solvents cannot be used. The main robot cables are IP65.